

RESEARCH ARTICLE

Some Basic Results in ν -Normed Spaces

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Abstract

In this paper, we introduce the notion of a directed preserving generator (d.p.g.) from $\mathbb{R}$ into $\mathbb{R}$. This d.p.g. can be used to construct new fields which generally have the same properties as $\mathbb{R}$, except that some properties are affected by d.p.g. itself. With this new field, a ν -normed space will be formed. Some of the basic properties of this normed space are also discussed.

Keywords: field, normed space, Banach space, bounded operator.

1. Introduction

Sometimes we can discover new things by changing our point of view of something. Classical Banach spaces are defined as a complete normed space over the field $\mathbb{R}$ or $\mathbb{C}$. In this paper, we will use a new field called ν -non-Newtonian field ${}_{\nu}\mathbb{R}$ which has similar properties to $\mathbb{R}$. Using this ${}_{\nu}\mathbb{R}$ which will be constructed in this section, then we can define ν -non-Newtonian normed spaces over ν -non-Newtonian field ${}_{\nu}\mathbb{R}$. To simplify, we will just state the function needed. So, if the function is ν , the notion ν -normed spaces over a field ${}_{\nu}\mathbb{R}$ will be used if it is not ambiguous.

This change in point of view was started by Grossman and Katz by moving the field $\mathbb{R}$ by using a function called a generator. A function $\alpha : \mathbb{R} \rightarrow \mathbb{R}$ is called a *generator function* if it is an injective function [9]. Many studies have used generators with this definition in several fields such as calculus [1], α -fixed point theory [2, 3], and some special α -Banach spaces [4, 5, 6, 7, 8, 10, 11]. Unfortunately, the injective nature of this generator is not strong enough to guarantee that the field ${}_{\alpha}\mathbb{R}$ generated by α has similar properties as its counterpart $\mathbb{R}$. Therefore, we define the stronger generator as follows.

Definition 1. A function $\nu : \mathbb{R} \rightarrow \mathbb{R}$ is called a directed preserving generator (g.d.p) if the function ν satisfies the following conditions:

- (i) one-one and continue,
- (ii) for any $a, b \in \mathbb{R}$ and $a \leq b$, we have $\nu(a) \dot{\leq} \nu(b)$ in ${}_{\nu}\mathbb{R}$, and
- (iii) for any $a, b \in \mathbb{R}$, there exists $\nu(c) \in {}_{\nu}\mathbb{R}$ such that $\nu(a) \dot{\leq} \nu(c)$ and $\nu(b) \dot{\leq} \nu(c)$ in ${}_{\nu}\mathbb{R}$.

The existence of $c \in \mathbb{R}$ in (iii) is just the implication of (i) and (ii). Using this new definition, the function $\alpha : \mathbb{R} \rightarrow \mathbb{R}$ which is defined as

$$\alpha(x) = \begin{cases} 0, & \text{if } x = 0 \\ \frac{1}{x}, & \text{otherwise} \end{cases}$$

is a generator that fails to be a g.d.p.

The continuity of g.d.p. ν will guarantee the existence of $\dot{0}$ and $\dot{1}$, where $\dot{0}$ and $\dot{1}$ respectively denote the addition identity and multiplication identity, i.e., $\nu(0) = \dot{0}$ and $\nu(1) = \dot{1}$. In the case $\nu = \exp$, clearly $\dot{0} = 1$ and $\dot{1} = e$. The property (ii) of d.p.g. ensures that the order in ${}_{\nu}\mathbb{R}$ does not reverse the original order in $\mathbb{R}$, while (iii) ensures that there is always an element in ${}_{\nu}\mathbb{R}$ greater than $\nu(a), \nu(b) \in {}_{\nu}\mathbb{R}$, i.e., the elements of ${}_{\nu}\mathbb{R}$ (depend on g.d.p. ν) are going to $-\infty$ and $+\infty$.

Before going any further, for any $\dot{a}, \dot{b} \in {}_{\nu}\mathbb{R}$, the arithmetics applied in a set of scalars ${}_{\nu}\mathbb{R}$ is defined as follows

$$\begin{aligned}\dot{a} + \dot{b} &= \nu \left(\nu^{-1}(\dot{a}) + \nu^{-1}(\dot{b}) \right) \\ \dot{a} - \dot{b} &= \nu \left(\nu^{-1}(\dot{a}) - \nu^{-1}(\dot{b}) \right) \\ \dot{a} \times \dot{b} &= \nu \left(\nu^{-1}(\dot{a}) \times \nu^{-1}(\dot{b}) \right) \\ \dot{a} / \dot{b} &= \nu \left(\nu^{-1}(\dot{a}) / \nu^{-1}(\dot{b}) \right) \\ |\dot{a}| &= \nu \left(\left| \nu^{-1}(\dot{a}) \right| \right) = \begin{cases} \dot{a} & , \text{ if } \dot{a} > \dot{0} \\ \dot{0} & , \text{ if } \dot{a} = \dot{0} \\ \dot{0} - \dot{a} & , \text{ if } \dot{a} < \dot{0} \end{cases} \\ \sqrt{\dot{a}^2} &= |\dot{a}| \\ \dot{a}^p &= \nu \left(\left[\nu^{-1}(\dot{a}) \right]^p \right)\end{aligned}$$

Using these arithmetics, for any $\dot{a}, \dot{b}, \dot{c} \in {}_{\nu}\mathbb{R}$ and a d.p.g. ν we have

$$\begin{aligned}\dot{a} + (\dot{b} + \dot{c}) &= \nu \left(\nu^{-1}(\dot{a}) + \nu^{-1}(\dot{b} + \dot{c}) \right) \\ &= \nu \left(\nu^{-1}(\dot{a}) + \nu^{-1} \left[\nu \left(\nu^{-1}(\dot{b}) + \nu^{-1}(\dot{c}) \right) \right] \right) \\ &= \nu \left(\nu^{-1}(\dot{a}) + \nu^{-1}(\dot{b}) + \nu^{-1}(\dot{c}) \right) \\ &= \nu \left(\nu^{-1} \left[\nu \left(\nu^{-1}(\dot{a}) + \nu^{-1}(\dot{b}) \right) \right] + \nu^{-1}(\dot{c}) \right) \\ &= \nu \left(\nu^{-1} [\dot{a} + \dot{b}] + \nu^{-1}(\dot{c}) \right) \\ &= (\dot{a} + \dot{b}) + \dot{c},\end{aligned}$$

and

$$\begin{aligned}\dot{a} + \dot{0} &= \nu \left(\nu^{-1}(\dot{a}) + \nu^{-1}(\dot{0}) \right) \\ &= \nu \left(\nu^{-1}(\dot{a}) + 0 \right) \\ &= \nu \left(\nu^{-1}(\dot{a}) \right) = \dot{a}.\end{aligned}$$

Similarly, it is easy to see that ${}_{\nu}\mathbb{R}$ is an abelian group under addition. Since

$$\dot{a} \times \dot{1} = \nu \left(\nu^{-1}(\dot{a}) \times \nu^{-1}(\dot{1}) \right) = \nu \left(\nu^{-1}(\dot{a}) \right) = \dot{a}$$

and

$$\begin{aligned}
 \dot{a} \dot{\times} (\dot{b} \dot{+} \dot{c}) &= \mathfrak{v} \left(\mathfrak{v}^{-1}(\dot{a}) \times \mathfrak{v}^{-1}(\dot{b} \dot{+} \dot{c}) \right) \\
 &= \mathfrak{v} \left(\mathfrak{v}^{-1}(\dot{a}) \times \mathfrak{v}^{-1} \left[\mathfrak{v} \left(\mathfrak{v}^{-1}(\dot{b}) + \mathfrak{v}^{-1}(\dot{c}) \right) \right] \right) \\
 &= \mathfrak{v} \left(\left[\mathfrak{v}^{-1}(\dot{a}) \times \mathfrak{v}^{-1}(\dot{b}) \right] + \left[\mathfrak{v}^{-1}(\dot{a}) \times \mathfrak{v}^{-1}(\dot{c}) \right] \right) \\
 &= \mathfrak{v} \left(\mathfrak{v}^{-1} \left[\mathfrak{v} \left(\mathfrak{v}^{-1}(\dot{a}) \times \mathfrak{v}^{-1}(\dot{b}) \right) \right] + \mathfrak{v}^{-1} \left[\mathfrak{v} \left(\mathfrak{v}^{-1}(\dot{a}) \times \mathfrak{v}^{-1}(\dot{c}) \right) \right] \right) \\
 &= \mathfrak{v} \left(\mathfrak{v}^{-1} \left[\dot{a} \dot{\times} \dot{b} \right] + \mathfrak{v}^{-1} \left[\dot{a} \dot{\times} \dot{c} \right] \right) \\
 &= \left[\dot{a} \dot{\times} \dot{b} \right] \dot{+} \left[\dot{a} \dot{\times} \dot{c} \right],
 \end{aligned}$$

some routine calculations will show that $\mathfrak{v}\mathbb{R}$ is a field. Indeed, the properties of d.p.g. assure that $\mathfrak{v}\mathbb{R}$ is a complete field. Therefore, $\mathfrak{v}\mathbb{R}$ can be used to form a new kind of normed space.

2. $\mathfrak{v}$ -Normed spaces

The previous section shows that there are new fields that can be formed from $\mathbb{R}$. If we can find an isomorphism from $\mathbb{R}$ onto $\mathfrak{v}\mathbb{R}$, then we can form $\mathfrak{v}$ -normed spaces over $\mathfrak{v}\mathbb{R}$.

Let $\mathfrak{v}$ and μ be d.p.g. and define an isomorphism $\mathfrak{u} : \mu\mathbb{R} \rightarrow \mathfrak{v}\mathbb{R}$ as $\mathfrak{u}(x) = \mathfrak{v}(\mu^{-1}(x))$. Then for any $\dot{a}, \dot{b} \in \mu\mathbb{R}$

$$\begin{aligned}
 \mathfrak{u}(\dot{a} \dot{+} \dot{b}) &= \mathfrak{v} \left(\mu^{-1}(\dot{a} \dot{+} \dot{b}) \right) \\
 &= \mathfrak{v} \left(\mu^{-1} \left[\mu \left(\mu^{-1}(\dot{a}) + \mu^{-1}(\dot{b}) \right) \right] \right) \\
 &= \mathfrak{v} \left(\mu^{-1}(\dot{a}) + \mu^{-1}(\dot{b}) \right) \\
 &= \mathfrak{v} \left(\mu^{-1}(\dot{a}) \right) \dot{+} \mathfrak{v} \left(\mu^{-1}(\dot{b}) \right) \\
 &= \mathfrak{u}(\dot{a}) \dot{+} \mathfrak{u}(\dot{b})
 \end{aligned}$$

and

$$\begin{aligned}
 \mathfrak{u}(\dot{a} \dot{\times} \dot{b}) &= \mathfrak{v} \left(\mu^{-1}(\dot{a} \dot{\times} \dot{b}) \right) \\
 &= \mathfrak{v} \left(\mu^{-1} \left[\mu \left(\mu^{-1}(\dot{a}) \times \mu^{-1}(\dot{b}) \right) \right] \right) \\
 &= \mathfrak{v} \left(\mu^{-1}(\dot{a}) \times \mu^{-1}(\dot{b}) \right) \\
 &= \mathfrak{v} \left(\mu^{-1}(\dot{a}) \right) \dot{\times} \mathfrak{v} \left(\mu^{-1}(\dot{b}) \right) \\
 &= \mathfrak{u}(\dot{a}) \dot{\times} \mathfrak{u}(\dot{b}).
 \end{aligned}$$

Since $\mu\mathbb{R}$ and $\mathfrak{v}\mathbb{R}$ are fields, we have $\mathfrak{u}(\dot{a} \dot{-} \dot{b}) = \mathfrak{u}(\dot{a}) \dot{-} \mathfrak{u}(\dot{b})$ and $\mathfrak{u}(\dot{a} \dot{\div} \dot{b}) = \mathfrak{u}(\dot{a}) \dot{\div} \mathfrak{u}(\dot{b})$ for any $\dot{b} \neq \dot{0}$. Considering the properties of d.p.g. $\mathfrak{v}$ and μ , we conclude that $\mathfrak{u}(x)$ is a field isomorphism. If μ is an identity mapping, i.e. $\mu(x) = x$, and $\mathfrak{v}$ be any d.p.g., then $\mathfrak{u}$ is an isomorphism from $\mathbb{R}$ onto $\mathfrak{v}\mathbb{R}$.

Now we are ready to discuss ν -normed space X . Using the isomorphism defined above, for any $x, y \in X$ we have

$$\iota(\lambda\|x\| + \|y\|) = \lambda \dot{\times} \|\dot{x}\| + \|\dot{y}\|.$$

Therefore, the followings are hold

- (i) $\|\dot{x}\| \dot{=} \dot{0}$ implies $\|x\| = \iota^{-1}(\|\dot{x}\|) = \iota^{-1}(\dot{0}) = \iota^{-1}(\nu(0)) = 0$ and by the classical normed space rule we get $x = 0 \in X$. On the contrary, for $x = 0$, $\|\dot{0}\| = \iota(\|0\|) = \dot{0}$,
- (ii) $\|\dot{\lambda \dot{\times} x}\| \dot{=} \iota(\|\lambda x\|) \dot{=} \iota(|\lambda| \|x\|) \dot{=} |\lambda| \dot{\times} \iota(\|x\|) \dot{=} |\lambda| \dot{\times} \|\dot{x}\|$,
- (iii) $\|\dot{x+y}\| \dot{=} \iota(\|x+y\|) \dot{=} \iota(\|x\| + \|y\|) \dot{=} \|\dot{x}\| + \|\dot{y}\|$.

These facts give the following definition

Definition 2. Let X be a vector space over the field ${}_{\nu}\mathbb{R}$. The function $\|\cdot\| : X \rightarrow {}_{\nu}\mathbb{R}^+$ is called a ν -norm on X if it satisfies

- (i) $\|\dot{x}\| \dot{\geq} \dot{0}$ and $\|\dot{x}\| \dot{=} \dot{0}$ if and only if $x = 0$,
- (ii) $\|\dot{\lambda \dot{\times} x}\| \dot{=} |\lambda| \dot{\times} \|\dot{x}\|$,
- (iii) $\|\dot{x+y}\| \dot{\leq} \|\dot{x}\| + \|\dot{y}\|$

for all $x, y \in X$ and $\lambda \in {}_{\nu}\mathbb{R}$. The ordered pair $(X, \|\cdot\|)$ is called ν -normed space.

If the context being discussed is clear, then X will be preferred over $(X, \|\cdot\|)$. By using property (iii) in the definition or directly using the isomorphism ι , for all $x, y \in X$ we have

$$\|\dot{x}\| \dot{=} \iota(\|x\|) \dot{\leq} \iota(\|x \dot{-} y\| + \|y\|) \dot{=} \|\dot{x \dot{-} y}\| + \|\dot{y}\|.$$

Similarly

$$\|\dot{y}\| \dot{=} \iota(\|y\|) \dot{\leq} \iota(\|y \dot{-} x\| + \|x\|) \dot{=} \|\dot{x \dot{-} y}\| + \|\dot{x}\|.$$

Therefore

$$\begin{aligned} |\|\dot{x}\| - \|\dot{y}\|| &\dot{=} \max \left\{ \|\dot{x}\| - \|\dot{y}\|, \|\dot{y}\| - \|\dot{x}\| \right\} \\ &\dot{\leq} \|\dot{x \dot{-} y}\|. \end{aligned}$$

The last inequality shows that the function $x \mapsto \|\dot{x}\|$ is a ν -continuous function. Furthermore, for any $x, x_0, y, y_0 \in X$ and $\lambda, \lambda_0 \in {}_{\nu}\mathbb{R}$

$$\|\dot{(x+y) \dot{-} (x_0+y_0)}\| \dot{\leq} \|\dot{x \dot{-} x_0}\| + \|\dot{y \dot{-} y_0}\|$$

and

$$\begin{aligned} \|\dot{\lambda x \dot{-} \lambda_0 x_0}\| &\dot{\leq} \|\dot{\lambda x \dot{-} \lambda x_0}\| + \|\dot{\lambda x_0 \dot{-} \lambda_0 x_0}\| \\ &\dot{=} |\lambda| \dot{\times} \|\dot{x \dot{-} x_0}\| + |\lambda_0| \|\dot{\lambda \dot{-} \lambda_0}\|. \end{aligned}$$

The continuity of a ν -norm function implies that the mappings $(x, y) \mapsto x+y$ and $(\lambda, y) \mapsto \lambda \dot{\times} y$ are ν -continuous from X into X . After knowing the ν -continuity of these mappings, it is natural to define the convergence of sequences in ν -normed spaces. Note that while discussing some concepts related to sequences, since we use $\mathbb{N}$ as a directed set, it must be understood that the natural numbers being used are in the original order, not as outputs of d.p.g. ν .

Definition 3. Let (x_n) be a sequence in ν -normed space X . The sequence (x_n) is said to be ν -Cauchy if for any $\varepsilon > 0$, there is $N_\varepsilon \in \mathbb{N}$ such that $\|x_n - x_m\| < \varepsilon$ whenever $n, m \geq N_\varepsilon$. The sequence (x_n) ν -converges to an element $x \in X$ if for any $\varepsilon > 0$, there is $N_\varepsilon \in \mathbb{N}$ such that $\|x - x_n\| < \varepsilon$ whenever $n \geq N_\varepsilon$. In this case, x is called ν -limit point of (x_n) and denoted by $\nu\text{-}\lim (x_n) = x$.

The previous discussions show that we can use the ν -norm function to form the topology for a vector space X with $\mathbb{F} = {}_\nu\mathbb{R}$. The elements of this ν -norm topology are any neighborhoods of $x \in X$.

Definition 4. Let X be ν -normed space and $x \in X$. The closed ball centered at x with a radii $r > 0$ is the set $\{y \in X : \|x - y\| \leq r\}$ and the open ball is the set $\{y \in X : \|x - y\| < r\}$. The sphere with a center at x and a radii r is the set $\{y \in X : \|x - y\| = r\}$.

If $x = 0$ and $r = 1$, then they are called a unit closed ball, unit open ball, and unit sphere which are respectively denoted by ${}_ \nu\overline{B}_X$, ${}_ \nu B_X$, and ${}_ \nu S_X$.

Definition 5. A ν -normed space is ν -Banach (complete) space if any ν -Cauchy sequence in X ν -converges to an element $x \in X$.

Çakmak and Başar [4] showed that some sequence spaces of scalars are Banach space with d.p.g. $\nu = \exp$. As stated before, this result generally doesn't hold for any generator, unless satisfies d.p.g. conditions.

Let X be a vector space over a field ${}_ \nu\mathbb{R}$, $A \subset X$, $x, y \in A$, and $\lambda \in (0, 1)$ and $\lambda x + (1 - \lambda)y \in A$, then A is called a *convex set*. A is a *balanced set* if for any $|\lambda| \leq 1$, we have $\lambda A \subset A$. If for any $z \in X$, there is $\lambda_z > 0$ such that $z \in \beta A$ whenever $\beta > \lambda_z$, then A is called *absorbing*.

Proposition 1. Any ball in a ν -normed space is convex. Furthermore, if the ball is centered at the origin, then the ball is balanced and absorbing.

Proof. Let ${}_ \nu B_r(x)$ be any ball centered at x with a radius r . Take any $y, z \in {}_ \nu B_r(x)$ and $0 < \lambda < 1$, then

$$\begin{aligned} \|\lambda y + (1 - \lambda)z - x\| &= \|\lambda y + (1 - \lambda)z - \lambda x - (1 - \lambda)x\| \\ &= \|\lambda(y - x) + (1 - \lambda)(z - x)\| \\ &\leq \lambda\|y - x\| + (1 - \lambda)\|z - x\| \\ &\leq \lambda r + (1 - \lambda)r. \end{aligned}$$

Therefore, $\lambda y + (1 - \lambda)z \in {}_ \nu B_r(x)$.

Now, take a ball ${}_ \nu B_r(0)$ and $|\lambda| \leq 1$. Then, for any $y \in {}_ \nu B_r(0)$, we get $\|\lambda y\| \leq \|\lambda\| \|y\|$ and hence $\lambda y \in {}_ \nu B_r(0)$. This shows that ${}_ \nu B_r(0)$ is a balanced set. Indeed, for any $x \in X$ and $\beta > \frac{\|x\|}{r}$, then $x \in \beta {}_ \nu B_r(0)$. Thus ${}_ \nu B_r(0)$ is absorbing. $\square$

Let A be any subset of a ν -normed space X . The closure of A , denoted by $\overline{A}$, is an intersection of all closed sets in X containing A . It is well known that $\overline{A}$ contains all ν -limit points. Since for any $x, y \in X$ and $x \neq y$, we can find $r > 0$ such that ${}_ \nu B_r(x) \cap {}_ \nu B_r(y) = \emptyset$ which shows that ν -norm topology is Hausdorff, and the ν -limit point is unique. The interior of A is the union of all open subsets of A , i.e., the largest open set containing A and denote by A° .

Proposition 2. Let A be any convex subset of a ν -normed space X . Then $\overline{A}$ and A° are convex sets.

Proof. Let $x, y \in \overline{A}$, $x_n \rightarrow x$ and $y_n \rightarrow y$. Then, for any $\lambda \in (\dot{0}, \dot{1})$

$$\|\lambda x + (\dot{1} - \lambda) y - \lambda x_n - (\dot{1} - \lambda) y_n\| \leq \lambda \|x - x_n\| + (\dot{1} - \lambda) \|y - y_n\|$$

and hence $\lambda x_n + (\dot{1} - \lambda) y_n \rightarrow \lambda y + (\dot{1} - \lambda) x$. Therefore, $\lambda y + (\dot{1} - \lambda) x \in \overline{A}$ which shows that $\overline{A}$ is a convex set.

Now, let $x, y \in A^\circ$. Then, for any $\lambda \in (\dot{0}, \dot{1})$

$$\lambda x + (\dot{1} - \lambda) y \in \lambda A^\circ + (\dot{1} - \lambda) A^\circ \subset A.$$

Since A is a convex set, it follows that A° is convex. $\square$

3. Bounded operators

This section will discuss the mappings between ν -normed space X and Y . It is well known that a mapping $T : X \rightarrow Y$ is linear if $T(x + y) = Tx + Ty$ and $T(\lambda x) = \lambda T(x)$ for any $x, y \in X$ and $\lambda \in {}_\nu\mathbb{R}$. From elementary calculus, the mapping $f : X \rightarrow Y$ is said to be continuous if, for an arbitrary $\varepsilon > 0$, there is $\delta = \delta_\varepsilon > 0$ such that $|f(x) - f(y)| < \varepsilon$ whenever $|x - y| < \delta$. Since we can form a ν -norm topology for ν -normed spaces X and Y , we can define the continuous linear operator as in the following definition.

Definition 6. Let X and Y be ν -normed spaces and $T : X \rightarrow Y$ be a linear operator. T is a continuous operator if it is continuous between X and Y , where X and Y are considered topological spaces under ν -norm topology.

Note that a subset A of a ν -normed space X is bounded if $\|x\| \leq M$ for any $x \in A$ and $M < \infty$, i.e. $A \subset {}_\nu B_M(0)$ for a large M .

Proposition 3. Let X and Y be ν -normed spaces and $T : X \rightarrow Y$ be a linear operator. The following conditions are equivalent:

- (i) T is continuous,
- (ii) T is continuous at 0,
- (iii) T is uniformly continuous,
- (iv) There is a constant $M > 0$ such that

$$\|Tx\| \leq M\|x\|$$

for all $x \in X$.

- (v) $T({}_\nu B_X)$ is a bounded set in Y .

Proof. (i) $\rightarrow$ (ii) is obvious.

(ii) $\rightarrow$ (i). Let (x_n) be any sequence ν -converges to $x \in X$. Since T continuous at 0,

$$\|Tx - Tx_n\| = \|T(x - x_n)\| \rightarrow \dot{0},$$

or $Tx_n \rightarrow Tx$. Thus, T is a continuous operator.

(ii) $\rightarrow$ (iii). The linearity and continuity of T at 0 imply that for any $\dot{\varepsilon} > \dot{0}$, there is $\dot{\delta} = \dot{\delta}_\varepsilon \dot{\varepsilon} > \dot{0}$ such that $\|Tx\| < \dot{\varepsilon}$ whenever $\|x\| < \dot{\delta}$. Since X is a ν -normed space, there is $x_1, x_2 \in X$ such that $x_1 = x_2$. Thus, $\|Tx_1 - Tx_2\| < \dot{\varepsilon}$ whenever $\|x_1 - x_2\| < \dot{\delta}$. Since x is arbitrary and $\dot{\delta}$ just depend on $\dot{\varepsilon}$, T is a uniformly continuous operator.

(iii) $\rightarrow$ (i) is obvious.

(iii) $\rightarrow$ (iv). $\|x\| < \delta$ implies $\|Tx\| < \varepsilon$. For any $x \in X$, put $y = \frac{\delta}{2\|x\|}x$. Then $\|y\| < \delta$ and hence $\|Ty\| < \varepsilon$. The linearity of T will give

$$\|Tx\| = \frac{2\|x\|}{\delta} \|Ty\| < \frac{2\varepsilon}{\delta} \|x\|.$$

Set $M = \frac{2\varepsilon}{\delta}$ to complete the proof.

(iv) $\rightarrow$ (iii). Taking a sequence (x_n) that converges to 0, then $\|x_n\| \rightarrow 0$ and hence $\|Tx_n\| \rightarrow 0$.

(iv) $\rightarrow$ (v). The equivalence can be done by taking $x \in {}_\nu B_X$.

(v) $\rightarrow$ (iv). Let $T({}_\nu B_X)$ be a bounded set, i.e., there is $M > 0$ such that $\|T({}_\nu B_X)\| \leq M$. Put $y = \frac{x}{\|x_n\|} \in {}_\nu B_X$, then

$$\|Tx\| = \|x\| \|Ty\| \leq M \|x\|$$

and the proof is complete. $\square$

Proposition 3 says that the notion of continuity and boundedness of linear operator T are interchangeable. Therefore, the following definition is equivalent to Definition 6.

Definition 7. Let X and Y be ν -normed spaces and $T : X \rightarrow Y$ be a linear operator. T is bounded if $T(A)$ is bounded for any bounded set $A \subset X$. $B(X, Y)$ stands for a collection of all bounded linear operators from X into Y .

The equivalence of (iv) and (v) in Proposition 3 gives a term called *operator norm* $\|T\|$ which is defined as

$$\|T\| = \sup \left\{ \|Tx\| : x \in {}_\nu B_X \right\}.$$

Indeed, the number $\|T\|$ is the smallest number that satisfies (iv). To see this, assume the contrary, that is $0 \leq M < \|T\|$. Then, for any $x \in {}_\nu B_X$

$$\|Tx\| = \sup \left\{ \|Tx\| : x \in {}_\nu B_X \right\} > M \geq M \|x\|$$

which contradicts the boundedness of T .

Theorem 1. Let X be a ν -normed space and Y be a ν -Banach space. Then $B(X, Y)$ is a ν -Banach space.

Proof. It is easy to see that $B(X, Y)$ is a ν -normed space under the operator norm. Let (T_n) be a ν -Cauchy sequence in $B(X, Y)$. Then, for each $x \in X$

$$\|T_n x - T_m x\| \leq \|T_n - T_m\| \|x\|.$$

Since Y is a ν -Banach space, $T_n x$ converges to some element $y \in Y$. Let $Tx = \nu\text{-}\lim T_n x$. Then, for any $x \in {}_\nu B_X$

$$\|Tx - T_m x\| \leq \|Tx - T_n x\| + \|T_n x - T_m x\|.$$

Taking the supremum of both sides gives $\|T - T_m\| \rightarrow 0$. Clearly, $T \in B(X, Y)$ and the proof is complete. $\square$

Concluding Remark Since $\|\cdot\| \in {}_\nu \mathbb{R}$ and $\|\cdot\| \in \mathbb{R}$, by deploying the isomorphism ι , all the results in this paper are also true for classical normed spaces.

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